

# A SCHUR TYPE THEOREM FOR ALMOST COSYMPLECTIC MANIFOLDS WITH KAEHLERIAN LEAVES

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## Abstract

In this study, we give a Schur type theorem for almost cosymplectic manifolds with Keahlerian leaves.

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## 1. Introduction

Let  $M$  be a Riemannian manifold with curvature tensor  $R$ . The sectional curvature of a 2-plane  $\alpha$  in a tangent space  $T_P M$  is defined by  $K(\alpha, P) = R(X, Y, Y, X)$ , where  $\{X, Y\}$  is an orthonormal basis of  $T_P M$ . The classical theorem of F. Schur says that if  $M$  is a connected manifold of dimension  $n \geq 3$  and in any point  $P \in M$  the curvature  $K(\alpha, P)$  does not depend on  $\alpha \in T_P M$  then it does not depend on the point  $P$  too, i.e. it is a global constant. Such a manifold is called a manifold of constant sectional curvature. The Schur's theorem has been studied by many authors for different structures [11]. In 1989, Nobuhiro improves the Schur's theorem and gets a new version for locally symmetric spaces [10]. In 2001, Kassabov considers connected  $2n$ -dimensional almost Hermitian manifold  $M$  to be of pointwise constant antiholomorphic sectional curvature  $\nu(p)$ ,  $p \in M$  and proves that  $\nu$  is a global constant [6]. In 2006, Cho defines a contact strongly pseudo-convex  $CR$  space-form using the Tanaka-Webster connection in a way similar to the Sasakian space form and then he studies the geometry of such spaces. He presents a Schur type theorem for such structures [7]. The notion of an almost cosymplectic manifold was introduced by Goldberg and Yano in 1969, [19]. The simplest examples of such manifolds are those being the products (possibly local) of almost Kaehlerian manifolds and the real line  $\mathbb{R}$  or the circle  $S^1$ . Curvature properties of almost cosymplectic manifolds were studied mainly by Goldberg and Yano [12], Olszak [13], [14], Kirichenko [15] and Endo [16]. We

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relate some of them in a historical order. A cosymplectic manifold of constant curvature is necessarily locally flat [17]. The existence of locally flat cosymplectic manifolds is obvious. In fact, they are locally products of locally flat Kaehlerian manifolds and the real line (for instance,  $C^n \times R$ ). If the curvature operator  $R$  of an almost cosymplectic manifold  $M$  commutes with the fundamental singular collineation  $\varphi$ , then  $M$  is normal, that is, it is a cosymplectic manifold [12]. In particular, an almost cosymplectic manifold of constant curvature is cosymplectic if and only if it is locally flat. Generalizing this, it is proved in [13], [14], that almost cosymplectic manifolds of non-zero constant curvature do not exist. For a conformally flat almost cosymplectic manifold of dimension  $\geq 5$ , the scalar curvature  $r$  is non-positive and the manifold is cosymplectic if and only if it is locally flat [13], [14]. If  $M$  is an almost cosymplectic manifold of constant  $\varphi$  sectional curvature then the scalar curvature  $r$  and the  $\varphi$  sectional curvature  $H$  satisfy the inequality  $n(n+1)H \geq r$ . This equality holds if and only if the manifold is cosymplectic [13].

In this paper, we concentrate on almost cosymplectic manifolds with Kaehlerian leaves and considering Schur's lemma on spaces of constant curvature, we get a new version for almost cosymplectic manifolds with Kaehlerian leaves.

## 2. Almost Cosymplectic Manifolds

Let  $M$  be a  $(2n+1)$ -dimensional differentiable manifold equipped with a triple  $(\varphi, \xi, \eta)$ , where  $\varphi$  is a type of  $(1, 1)$  tensor field,  $\xi$  is a vector field,  $\eta$  is a 1-form on  $M$  such that

$$(2.1) \quad \eta(\xi) = 1, \quad \varphi^2 = -I + \eta \otimes \xi,$$

which implies

$$(2.2) \quad \varphi\xi = 0, \quad \eta \circ \varphi = 0, \quad \text{rank}(\varphi) = 2n.$$

If  $M$  admits a Riemannian metric  $g$ , such that

$$(2.3) \quad \begin{aligned} g(\varphi X, \varphi Y) &= g(X, Y) - \eta(X)\eta(Y), \\ \eta(X) &= g(X, \xi), \end{aligned}$$

then  $M$  is said to have an almost contact structure  $(\varphi, \xi, \eta, g)$ . On such a manifold, the fundamental 2-form  $\Phi$  of  $M$  is defined by

$$\Phi(X, Y) = g(\varphi X, Y),$$

for any vector fields  $X, Y$  on  $M$ . An almost contact manifold  $(M, \varphi, \xi, \eta)$  is said to be normal if the Nijenhuis torsion

$$N_\varphi(X, Y) = [\varphi X, \varphi Y] - \varphi[\varphi X, Y] - \varphi[X, \varphi Y] + \varphi^2[X, Y] + 2d\eta(X, Y)\xi,$$

vanishes for any vector fields  $X, Y$  on  $M$ . As it is known that an almost contact metric structure is almost cosymplectic if and only if both  $\nabla\eta$  and  $\nabla\Phi$  vanish. A normal almost cosymplectic manifold is called a cosymplectic manifold. Let  $M$  be an almost cosymplectic manifold with structure  $(\varphi, \xi, \eta, g)$  and  $\mathcal{D}$  is the distribution of  $M$  defined by  $\mathcal{D} = \ker \eta$ . Since  $d\eta = 0$ ,  $\mathcal{D}$  is integrable and the  $(2n)$ -dimensional distribution is given by  $\varphi(\mathcal{D}) = \mathcal{D}$ . Also, we obviously have  $\xi$  is orthogonal to  $\mathcal{D}$ . Let  $N$  be a maximal integral submanifold of  $\mathcal{D}$ . So the vector field  $\xi$  restricted to integral submanifold  $N$  is the normal vector of  $N$ . Hence, there exists a Hermitian structure. Moreover, the tensor field  $\varphi$  induces an almost complex structure  $J$  ( $J^2 = -I$ ) on  $M$  by  $J\tilde{X} = \varphi\tilde{X}$  for any vector field  $\tilde{X}$  tangent to  $N$ . Let  $G$  be the Riemannian metric induced on  $N$  defined by  $G(\tilde{X}, \tilde{Y}) = g(\tilde{X}, \tilde{Y})$ . Then  $(J, G)$  becomes an almost Hermitian structure on  $N$  such that  $G(\tilde{X}, \tilde{Y}) = G(J\tilde{X}, J\tilde{Y})$  for any vector fields  $\tilde{X}$  and  $\tilde{Y}$  tangent to  $N$ . The fundamental 2-form  $\Omega$ ,  $\Omega(\tilde{X}, \tilde{Y}) = G(J\tilde{X}, \tilde{Y})$  of  $(J, G)$  induced on  $N$ . We also have  $\Omega(\tilde{X}, \tilde{Y}) = \Phi(X, Y)$ , that is,  $\Omega$  is the pull-back of the tensor field  $\varphi$  from  $M$  to  $N$ . As

a result,  $\Omega$  is closed, i.e.,  $d\Omega = 0$ . So the pair  $(J, G)$  is an almost Kaehlerian structure on  $N$  of  $\mathcal{D}$ . Therefore, when the structure  $J$  is complex,  $(J, G)$  becomes a Kaehlerian structure on  $N$ . If the structure  $(J, G)$  is Kaehlerian on every integral submanifold of the distribution  $\mathcal{D}$ , such manifold is said to be an almost cosymplectic manifold with Kaehlerian integral submanifold. Suppose that  $M$  is an almost cosymplectic manifold. Denote by  $A$  the  $(1, 1)$ -tensor field on  $M$  defined by

$$(2.4) \quad A = -\nabla\xi,$$

and by  $h$  the  $(1, 1)$ -tensor field given by the following relation

$$h = \frac{1}{2}\mathcal{L}_\xi\varphi,$$

where  $\mathcal{L}$  is the Lie derivative of  $g$ . Obviously,  $A(\xi) = 0$  and  $h(\xi) = 0$ . Moreover, the tensor fields  $A$  and  $h$  are symmetric operators and satisfy the following relations

$$(2.5) \quad \nabla_X\xi = -\varphi hX,$$

$$(2.6) \quad (\varphi \circ h)X + (h \circ \varphi)X = 0,$$

$$(2.7) \quad (\nabla_X\eta)Y = g(\varphi Y, hX),$$

$$(2.8) \quad \delta\eta = 0, \quad tr(h) = 0,$$

$$(2.9) \quad tr(A) = 0,$$

$$(2.10) \quad tr(\varphi A) = 0,$$

$$(2.11) \quad A\varphi + \varphi A = 0,$$

$$(2.12) \quad A\xi = 0,$$

$$(2.13) \quad (\nabla_X A)\xi = A^2X,$$

$$(2.14) \quad tr(A^2) = \|A^2\|,$$

for any vector fields  $X, Y$  on  $M$ . We also remark that

$$(2.15) \quad h = 0 \Leftrightarrow \nabla\xi = 0.$$

**2.1. Proposition.** *Let  $M$  be an almost cosymplectic manifold.  $M$  has Kaehlerian leaves if and only if it satisfies the condition*

$$(2.16) \quad (\nabla_X\varphi)Y = -g(\varphi AX, Y)\xi + \eta(Y)\varphi AX.$$

for any vector fields  $X, Y$  on  $M$  [1].

### 3. Basic Curvature Relations

In this section, we will briefly give the basic curvature relations. Let  $(M, \phi, \xi, \eta, g)$  be an almost cosymplectic manifold. We denote the curvature tensor and Ricci tensor of  $g$  by  $R$  and  $S$ , respectively. We define a self adjoint operator  $l = R(\cdot, \xi)\xi$  (The Jacobi operator with respect to  $\xi$ ). One easily see the followings.

**3.1. Proposition.** *Let  $M$  be an almost cosymplectic manifold. Then we have*

$$(3.1) \quad R(X, Y)\xi = (\nabla_Y\varphi h)X - (\nabla_X\varphi h)Y,$$

$$(3.2) \quad R(X, Y)\xi = -(\nabla_X A)Y + (\nabla_Y A)X,$$

$$(3.3) \quad R(X, \xi)\xi = -h^2X + \varphi(\nabla_\xi h)X,$$

$$(3.4) \quad (\nabla_\xi h)X = -\varphi R(X, \xi)\xi - \varphi h^2X,$$

$$(3.5) \quad R(X, \xi)\xi - \varphi R(\varphi X, \xi)\xi = -2[h^2X],$$

$$(3.6) \quad S(X, \xi) = -\sum_{i=1}^{2n+1} g((\nabla_{e_i}\varphi h)e_i, X),$$

$$(3.7) \quad \text{tr}(l) = S(\xi, \xi) = -\text{tr}(h^2).$$

for any vector fields  $X, Y$  on  $M$ .

By simple computations, we have the following proposition that will be used in the next important result.

**3.2. Proposition.** *For the curvature transformation of almost cosymplectic manifold with Kaehlerian leaves, we have*

$$(3.8) \quad R(X, Y)\varphi Z - \varphi R(X, Y)Z = g(AX, \varphi Z)AY - g(AY, \varphi Z)AX - g(AX, Z)\varphi AY \\ + g(AY, Z)\varphi AX - \eta(Z)\varphi(R(X, Y)\xi) - g(R(X, Y)\xi, \varphi Z)\xi,$$

and

$$(3.9) \quad R(\varphi X, \varphi Y)Z - R(X, Y)Z = \eta(Y)R(\xi, X, Z) + g(AZ, \varphi X)A\varphi Y - g(AZ, \varphi Y)A\varphi X \\ - g(AZ, X)AY + g(AZ, Y)AX - \eta(X)R(\xi, Y, Z) + \eta(X)\eta(Y)R(\xi, \xi).$$

**3.3. Proposition.** *If we denote*

$$P_\varphi(X, Y) = (\nabla_Y \varphi h)X - (\nabla_X \varphi h)Y,$$

and

$$P(X, Y) = (\nabla_Y h)X - (\nabla_X h)Y.$$

Then, we satisfy following relations

$$P_\varphi(X, Y) = \varphi P(X, Y), \\ \varphi P_\varphi(X, Y) = -P(X, Y) + 2g(hX, \varphi hY)\xi, \\ P_\varphi(X, Y) = -P_\varphi(Y, X).$$

**3.4. Proposition.** *Let  $M$  be an almost cosymplectic manifold. The necessary and sufficient condition for  $M$  to have pointwise constant  $\varphi$ -holomorphic sectional curvature  $H$  is*

$$(3.10) \quad 4R(X, Y, Z, W) = H [g(X, W)g(Z, Y) - g(X, Z)g(W, Y)] \\ - H [\eta(X)\eta(W)g(Z, Y) + \eta(Y)\eta(Z)g(X, W) \\ + 2g(X, \varphi Y)g(Z, \varphi W) - \eta(Y)\eta(W)g(X, Z) - \eta(X)\eta(Z)g(W, Y)] \\ + H [g(X, \varphi Z)g(W, \varphi Y) - g(X, \varphi W)g(Z, \varphi Y) \\ - g(AX, \varphi Z)g(AY, \varphi W) + g(AW, \varphi X)g(AZ, \varphi Y) \\ - g(AZ, \varphi X)g(AW, \varphi Y) + g(AX, \varphi W)g(AY, \varphi Z) \\ + 2g(AX, Z)g(AW, Y) - 2g(AX, W)g(AZ, Y) \\ + 4\eta(X)P_\varphi(Z, W, Y) + 4\eta(Z)P_\varphi(X, Y, W) \\ - 4\eta(W)P_\varphi(X, Y, Z) - 4\eta(X)\eta(W)P_\varphi(Z, \xi, Y) \\ - 4\eta(X)\eta(Z)P_\varphi(\xi, W, Y) - 4\eta(X)\eta(Y)P_\varphi(Z, W, \xi) \\ - 4\eta(Y)P_\varphi(Z, W, X) + 4\eta(Y)\eta(W)P_\varphi(Z, \xi, X) \\ + 4\eta(Y)\eta(Z)P_\varphi(\xi, W, X) + 4\eta(X)\eta(Z)P_\varphi(\xi, Y, W) \\ - 4\eta(X)\eta(W)P_\varphi(\xi, Y, Z)].$$

for all vector fields  $X, Y, Z, W$  in  $M$ .

*Proof.* For any vector fields  $X$  and  $Y \in \mathcal{D}$ , we have

$$(3.11) \quad g(R(X, \varphi X)X, \varphi X) = -Hg(X, X)^2$$

By (3.8) we get

$$(3.12) \quad R(X, \varphi Y, X, \varphi Y) = R(X, \varphi Y, Y, \varphi X) + g(AX, \varphi X)g(AY, \varphi Y) \\ - g(A\varphi Y, \varphi X)g(AX, Y) + g(A\varphi Y, \varphi Y)g(AX, X) \\ - g(A\varphi Y, X)g(AX, \varphi Y),$$

$$(3.13) \quad R(X, \varphi X, Y, \varphi X) = R(X, \varphi X, X, \varphi Y),$$

for  $X, Y \in \mathcal{D}$ . Submitting  $X + Y$  in (3.11), we see

$$\begin{aligned} & -H [2g(X, Y)^2 + 2g(X, X)g(X, Y) + 2g(X, Y)g(Y, Y) + g(X, X)g(Y, Y)] \\ & = \frac{1}{2} (gR(X + Y, \varphi X + \varphi Y)(X + Y), \varphi X + \varphi Y) + \frac{1}{2} H (g(X, X)^2 + g(Y, Y)^2), \end{aligned}$$

and because of (3.8) and (3.13) and the Bianchi identity

$$\begin{aligned} & -H [2g(X, Y)^2 + 2g(X, X)g(X, Y) + 2g(X, Y)g(Y, Y) + g(X, X)g(Y, Y)] \\ & = 2R(X, \varphi X, X, \varphi Y) + 2R(X, \varphi Y, Y, \varphi X) + R(X, Y, \varphi X, \varphi Y) \\ & + 2R(Y, \varphi Y, Y, \varphi X) + R(X, \varphi Y, X, \varphi Y) \\ & + \frac{1}{2} [g(AY, Y)g(A\varphi X, \varphi X) - g(AY, \varphi X)^2 - g(AX, X)g(A\varphi Y, \varphi Y) \\ & + g(AX, \varphi Y)^2], \end{aligned}$$

then because of (3.9) and (3.12), we get

$$(3.14) \quad \begin{aligned} & 2R(X, \varphi X, X, \varphi Y) + 2R(Y, \varphi X, Y, \varphi Y) + 3R(X, \varphi Y, Y, \varphi X) \\ & + R(X, Y, X, Y) + \frac{1}{2} [2g(AX, \varphi X)g(AY, \varphi Y) - 2g(AX, \varphi Y)g(AY, \varphi X) \\ & - 2g(AX, X)g(AY, Y)] + 4g(AX, Y)^2 - g(AX, \varphi Y)^2 \\ & + 2g(AX, \varphi X)g(AY, \varphi Y) + g(AY, Y)g(A\varphi X, \varphi X) \\ & - g(AY, \varphi X)^2 - g(AX, X)g(A\varphi Y, \varphi Y) \\ & = -H [2g(X, Y)^2 + 2g(X, X)g(X, Y) + 2g(X, Y)g(Y, Y) + g(X, X)g(Y, Y)] \end{aligned}$$

Replacing  $Y$  by  $-Y$  in (3.14) and summing it to (3.14) we have

$$(3.15) \quad \begin{aligned} & 3R(X, \varphi Y, Y, \varphi X) + R(X, Y, X, Y) = -H [2g(X, Y)^2 + g(X, X)g(Y, Y)] \\ & - 2g(AX, \varphi X)g(AY, \varphi Y) + g(AX, \varphi Y)g(AY, \varphi X) + 2g(AX, X)g(AY, Y) \\ & + 2g(AX, \varphi Y)^2 - 4g(AX, Y)^2 - \frac{1}{2} [g(AY, Y)g(A\varphi X, \varphi X) \\ & - g(AY, \varphi X)^2 - g(AX, X)g(A\varphi Y, \varphi Y)], \end{aligned}$$

By virtue of (3.15) we see

$$(3.16) \quad \begin{aligned} & 8R(X, Y, X, Y) = H [2g(X, \varphi Y)^2 + g(X, X)g(\varphi Y, \varphi Y) \\ & + 2g(X, Y)^2 + g(X, X)g(Y, Y)] \\ & - 4g(AX, \varphi X)g(AY, \varphi Y) + 8g(AX, \varphi Y)g(AY, \varphi X) \\ & + \frac{17}{2}g(AX, X)g(AY, Y) - \frac{11}{2}g(AX, Y)^2 - \frac{7}{2}g(AX, \varphi Y)^2 \\ & + \frac{1}{2}g(AY, Y)g(A\varphi X, \varphi X) - \frac{1}{2}g(AY, \varphi X)^2 + \frac{5}{2}g(AX, X)g(A\varphi Y, \varphi Y) \\ & - \frac{3}{2} [g(A\varphi Y, \varphi Y)g(A\varphi X, \varphi X) - g(AY, \varphi X)^2] \end{aligned}$$

We verify (3.16), replacing  $Y$  by  $\varphi Y$  in (3.15), together with (3.9) and (3.12)

$$(3.17) \quad \begin{aligned} & -H [2g(X, \varphi Y)^2 + g(X, X)g(\varphi Y, \varphi Y)] = 3R(X, Y, X, Y) \\ & + R(X, \varphi Y, Y, \varphi X) + 2g(AX, \varphi X)g(AY, \varphi Y) \\ & - 3g(AX, \varphi Y)g(AY, \varphi X) - \frac{7}{2}g(AX, X)g(AY, Y) + \frac{5}{2}g(AX, Y)^2 \\ & - g(AX, X)g(A\varphi Y, \varphi Y) + g(AX, \varphi Y)^2 \\ & + \frac{1}{2} [g(A\varphi Y, \varphi Y)g(A\varphi X, \varphi X) - g(A\varphi Y, \varphi X)^2], \end{aligned}$$

and because of (3.15)

$$\begin{aligned} & -H [2g(X, \varphi Y)^2 + g(X, X)g(\varphi Y, \varphi Y)] = 3R(X, Y, X, Y) \\ & - \frac{1}{3}R(X, Y, X, Y) - \frac{H}{3} [2g(X, Y)^2 + g(X, X)g(Y, Y)] \\ & + \frac{4}{3}g(AX, \varphi X)g(AY, \varphi Y) - \frac{8}{3}g(AX, \varphi Y)g(AY, \varphi X) \\ & - \frac{17}{6}g(AX, X)g(AY, Y) + \frac{11}{6}g(AX, Y)^2 + \frac{7}{6}g(AX, \varphi Y)^2 \\ & - \frac{1}{6}g(AY, Y)g(A\varphi X, \varphi X) + \frac{1}{6}g(AY, \varphi X)^2 - \frac{5}{6}g(AX, X)g(A\varphi Y, \varphi Y) \\ & + \frac{1}{2} [g(A\varphi Y, \varphi Y)g(A\varphi X, \varphi X) - g(A\varphi Y, \varphi X)^2] \end{aligned}$$

After simplification (3.16) follows. Therefore by a standard calculation we have

$$(3.18) \quad \begin{aligned} 8R(X, Y, X, Y) &= -3H [2g(X, \varphi Y)^2 + g(X, X)g(\varphi Y, \varphi Y)] \\ &+ H [2g(X, Y)^2 + g(X, X)g(Y, Y)] - 4g(AX, \varphi X)g(AY, \varphi Y) \\ &+ 8g(AX, \varphi Y)g(AY, \varphi X) + \frac{17}{2}g(AX, X)g(AY, Y) \\ &- \frac{11}{2}g(AX, Y)^2 - \frac{7}{2}g(AX, \varphi Y)^2 + \frac{1}{2}g(AY, Y)g(A\varphi X, \varphi X) \\ &- \frac{1}{2}g(AY, \varphi X)^2 + \frac{5}{2}g(AX, X)g(A\varphi Y, \varphi Y) \\ &- \frac{3}{2}[g(A\varphi Y, \varphi Y)g(A\varphi X, \varphi X) - g(A\varphi Y, \varphi X)^2]. \end{aligned}$$

for any  $X, Y \in \mathcal{D}$ . Firstly, replacing  $X = X + Z$  in (3.18) and then replacing  $Y = Y + W$  in obtained result and by using Bianchi identity and (2.6) we get

$$(3.19) \quad \begin{aligned} 48R(X, W, Z, Y) &= H [12g(X, Y)g(Z, W) \\ &- 12g(X, \varphi Y)g(Z, \varphi W) - 24g(X, \varphi W)g(Z, \varphi Y) \\ &- 12g(X, Z)g(Y, W) + 12g(X, \varphi Z)g(Y, \varphi W)] \\ &+ 3g(AX, \varphi Z)g(AY, \varphi W) - 3g(AX, \varphi Y)g(AZ, \varphi W) \\ &- 12g(AX, \varphi Z)g(AW, \varphi Y) + 12g(AX, \varphi Y)g(AW, \varphi Z) \\ &- 12g(AZ, \varphi X)g(AY, \varphi W) + 12g(AY, \varphi X)g(AZ, \varphi W) \\ &- 3g(AZ, \varphi X)g(AW, \varphi Y) + 3g(AY, \varphi X)g(AW, \varphi Z) \\ &+ 15g(AX, \varphi W)g(AY, \varphi Z) - 15g(AX, \varphi W)g(AZ, \varphi Y) \\ &+ 9g(AZ, \varphi Y)g(AW, \varphi X) - 9g(AY, \varphi Z)g(AW, \varphi X) \\ &+ 24g(AX, Z)g(AY, W) - 24g(AX, Y)g(AZ, W). \end{aligned}$$

where  $X, Y, Z, W \in \mathcal{D}$ . We now let  $X$  be an arbitrary vector field on  $M$ . Then we may write

$$X = X^T + \eta(X)\xi$$

where  $X^T$  denotes the horizontal part of  $X$ . Then we have all vector fields  $X, Y, Z, W$  in  $M$ .

$$(3.20) \quad \begin{aligned} R(X, Y, Z, W) &= R(X^T, Y^T, Z^T, W^T) \\ &+ \eta(X)R(\xi, Y^T, Z^T, W^T) + \eta(Y)R(X^T, \xi, Z^T, W^T) \\ &+ \eta(Z)R(X^T, Y^T, \xi, W^T) + \eta(W)R(X^T, Y^T, Z^T, \xi) \\ &+ \eta(X)\eta(Z)R(\xi, Y^T, \xi, W^T) + \eta(X)\eta(W)R(\xi, Y^T, Z^T, \xi) \\ &+ \eta(Y)\eta(Z)R(X^T, \xi, \xi, W^T) + \eta(Y)\eta(W)R(X^T, \xi, Z^T, \xi). \end{aligned}$$

If we use (3.19) and (3.20) the proof is completed.  $\square$

Moreover, from (3.10), we get

$$(3.21) \quad \begin{aligned} S(Y, Z) &= \frac{1}{2}[(n+1)H]\{g(Y, Z) - \eta(Y)\eta(Z)\} \\ &+ \eta(Z)\sum P_\varphi(E_i, Y, E_i) - \eta(Y)\sum P_\varphi(Z, E_i, E_i) \\ &+ \eta(Y)\eta(Z)\sum P_\varphi(\xi, E_i, E_i) - 2P_\varphi(\xi, Y, Z). \end{aligned}$$

for all vector fields  $X$  and  $Y$  in  $M$  where  $\{E_i\}$  ( $i = 1, 2, \dots, 2n+1$ ) is an arbitrary local orthonormal frame field on  $M$  since the trace of  $h$  vanishes, from (3.21), we have for the scalar curvature

$$(3.22) \quad \tau = n(n+1)H - 2Tr(h^2).$$

#### 4. A class of almost cosymplectic manifolds $\mathcal{D}$

There are two typical examples of contact manifolds; one is formed by the principal circle bundles over symplectic manifolds of integral class (including the odd-dimensional spheres) and the other is given by the unit tangent sphere bundles. The former admit a Riemannian metric which is Sasakian. Concerning the latter, in [20], it was proved that the associated  $CR$ -structure of a unit tangent sphere bundle  $T_1M$  with standard contact Riemannian structure is integrable if and only if the base manifold is of constant

curvature. Here, we note that the unit tangent sphere bundle of a space of constant curvature satisfies ([21])

$$(4.1) \quad g((\nabla_{X^T} h)Y^T, Z^T) = 0.$$

That is,  $h$  is  $\eta$ -parallel. Now, we consider a contact Riemannian manifold whose structure tensor  $h$  satisfies (4.1) and (3.4) simultaneously. Then

$$\begin{aligned} 0 &= g((\nabla_{X^T} h)Y^T, Z^T) = g((\nabla_{X-\eta(X)\xi} h)(Y-\eta(Y)\xi, Z-\eta(Z)\xi)) \\ &= g((\nabla_X h)Y, Z) - \eta(X)g((\nabla_\xi h)Y, Z) - \eta(Y)g((\nabla_X h)\xi, Z) \\ &\quad - \eta(Z)g((\nabla_X h)Y, \xi) + \eta(X)\eta(Y)g((\nabla_\xi h)\xi, Z) + \eta(Y)\eta(Z)g((\nabla_X h)\xi, \xi) \\ &\quad + \eta(Z)\eta(X)g((\nabla_\xi h)Y, \xi) - \eta(X)\eta(Y)\eta(Z)g((\nabla_\xi h)\xi, \xi). \end{aligned}$$

From the above equation, by using (2.6), (2.7) and using (3.4), we have

$$(4.2) \quad (\nabla_X h)Y = \eta(X)[- \varphi lY - \varphi h^2 Y] - \eta(Y)(\varphi h^2 X) - g(\varphi h^2 X, Y)\xi.$$

Moreover from (3.22) we have

$$(4.3) \quad P(X, Y) = \eta(X)\varphi lY - \eta(Y)\varphi lX - 2g(\varphi h^2 X, Y)\xi,$$

$$(4.4) \quad P_\varphi(X, Y) = -\eta(X)lY + \eta(Y)lX.$$

for any vector fields  $X$  and  $Y$ . Now we define a  $(1, 2)$ -tensor field  $Q_1(X, Y)$  by

$$\begin{aligned} Q_1(X, Y) &= (\nabla_X h)Y - \eta(X)[- \varphi lY - \varphi h^2 Y] \\ &\quad - \eta(Y)[\varphi h^2 X] + g(\varphi h^2 X, Y)\xi. \end{aligned}$$

**4.1. Definition.** The class  $\mathfrak{D}$  is given by the spaces of almost cosymplectic manifold with Kaehlerian leaves satisfying  $Q_1 = 0$ , that is

$$\mathfrak{D} = \{(M, \phi, \xi, \eta, g) : Q_1 = 0\}.$$

We can see that this class  $\mathfrak{D}$  is invariant under  $D$ -homothetic deformations [21].

**4.2. Lemma.** Let  $M$  be a space  $\in \mathfrak{D}$  then the eigenvalues of  $h$  are constant.

## 5. Shur Type Theorem

**5.1. Theorem.** Let  $M$  be an almost cosymplectic manifold with Kaehlerian leaves belonging to the class  $\mathfrak{D}$ . If the  $\varphi$ -holomorphic sectional curvature at any point of  $M$  is independent of the choice of  $\varphi$ -holomorphic section, then it is constant on  $M$  and the curvature tensor is given by

$$\begin{aligned} (5.1) \quad 4R(X, Y, Z, W) &= c[g(X, W)g(Z, Y) - g(X, Z)g(W, Y)] \\ &\quad - c[\eta(X)\eta(W)g(Z, Y) + \eta(Y)\eta(Z)g(X, W)] \\ &\quad + 2g(X, \varphi Y)g(Z, \varphi W) - \eta(Y)\eta(W)g(X, Z) \\ &\quad - \eta(X)\eta(Z)g(W, Y) \\ &\quad + H[g(X, \varphi Z)g(W, \varphi Y) - g(X, \varphi W)g(Z, \varphi Y) \\ &\quad - g(AX, \varphi Z)g(AY, \varphi W) + g(AW, \varphi X)g(AZ, \varphi Y) \\ &\quad - g(AZ, \varphi X)g(AW, \varphi Y) + g(AX, \varphi W)g(AY, \varphi Z) \\ &\quad + 2g(AX, Z)g(AW, Y) - 2g(AX, W)g(AZ, Y). \end{aligned}$$

for all vector fields  $X, Y, Z, W$  in  $M$ .

*Proof.* Suppose that  $M$  has pointwise constant  $\varphi$ -holomorphic sectional curvature  $H$ . Then, taking account of (4.2), (4.3) and (4.4), from (3.21) we obtain

$$(5.2) \quad \begin{aligned} S(Y, Z) &= \frac{1}{2}[(n+1)H]\{g(Y, Z) - \eta(Y)\eta(Z)\} \\ &\quad + Tr(l)\eta(Y)\eta(Z) + 2g(lY, Z), \end{aligned}$$

$$(5.3) \quad \tau = n(n+1)H + 3Tr(l).$$

From (4.2) and by using (2.16) and Lemma 4.2, we have

$$\begin{aligned} 2(\nabla_X S)(Y, Z) &= [(n+1)X(H)]\{g(Y, Z) - \eta(Y)\eta(Z)\} \\ &+ [2Tr(l) - (n+1)H]\{\eta(Z)g(Y, \nabla_X \xi) - \eta(Y)g(Z, \nabla_X \xi)\} \\ &+ 4g((\nabla_X l)Y, Z), \end{aligned}$$

which yields

$$\begin{aligned} (5.4) \quad \sum 2(\nabla_{E_i} S)(Y, E_i) &= \sum [(n+1)E_i(H)]\{g(Y, E_i) - \eta(Y)\eta(E_i)\} \\ &+ \sum [2Tr(l) - (n+1)H]\{\eta(Y)g(E_i, \nabla_{E_i} \xi) - \eta(E_i)g(Y, \nabla_{E_i} \xi)\} \\ &+ \sum 4g((\nabla_{E_i} l)Y, E_i) \\ &= (n+1)\sum E_i(H)g(Y, E_i) - (n+1)\xi(H)\eta(Y) + \sum 4g((\nabla_{E_i} l)Y, E_i). \end{aligned}$$

by the well-known formula

$$(\nabla_X \tau) = 2\sum (\nabla_{E_i} S)(X, E_i).$$

for any local orthonormal frame field  $\{E_i\}$  ( $i = 1, 2, \dots, 2n+1$ ) and by using (5.3), (5.4) and Lemma 4.2, we have

$$(n+1)\{XH - (\xi H)\eta(X)\} = 2n(n+1)XH.$$

This says that  $\xi H = 0$  and  $(n-1)XH = 0$ . Since  $n > 1$ , we see that  $H$  is constant, say  $c$ . by applying (4.2), (4.3) and (4.4) in Proposition 3.4, we obtain (5.1)  $\square$

**5.2. Definition.** A complete and simply connected almost cosymplectic manifold of class  $\mathfrak{D}$  with constant  $\varphi$ -holomorphic sectional curvature is said to be an almost cosymplectic space form.

So, from the proof of Proposition 3.4 and Theorem 5.1, we have,

**5.3. Theorem.** *Let  $M$  be a complete and simply connected almost cosymplectic space belonging to the class  $\mathfrak{D}$ . Then  $M$  is an almost cosymplectic space form if and only if the curvature tensor  $R$  is given by (5.1).*

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